

# Building a Simple CLI

Nathan Jones

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What could we talk about  
that would be worth 20  
minutes of your time?

# Agenda

1. Why and what is it?
2. Plan of attack
3. Step 1: Read from UART
4. Step 2: Simple commands
5. Step 3: Commands + values
6. Going further

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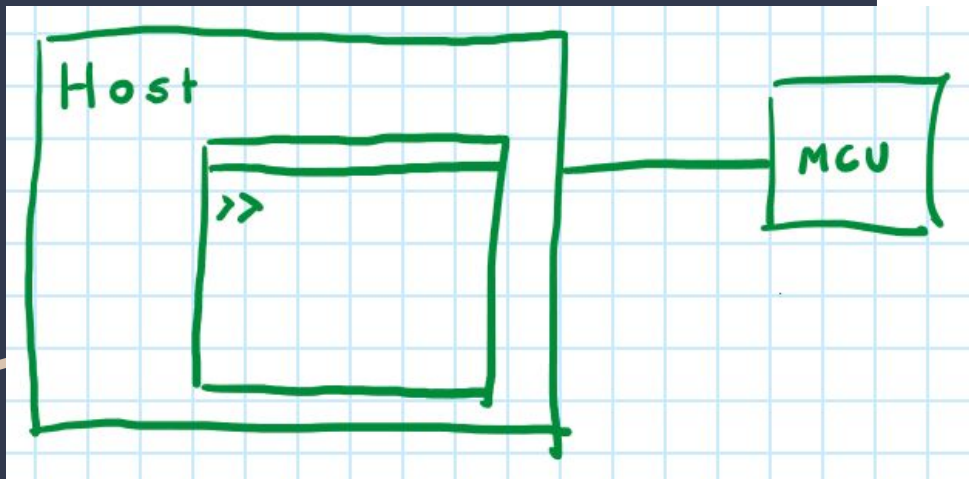


# Why and What is it?

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- Control tasks
- Query state
- REPL
- Load data/firmware
- On-chip debugging (Cortex-M)
- Monitor/small OS

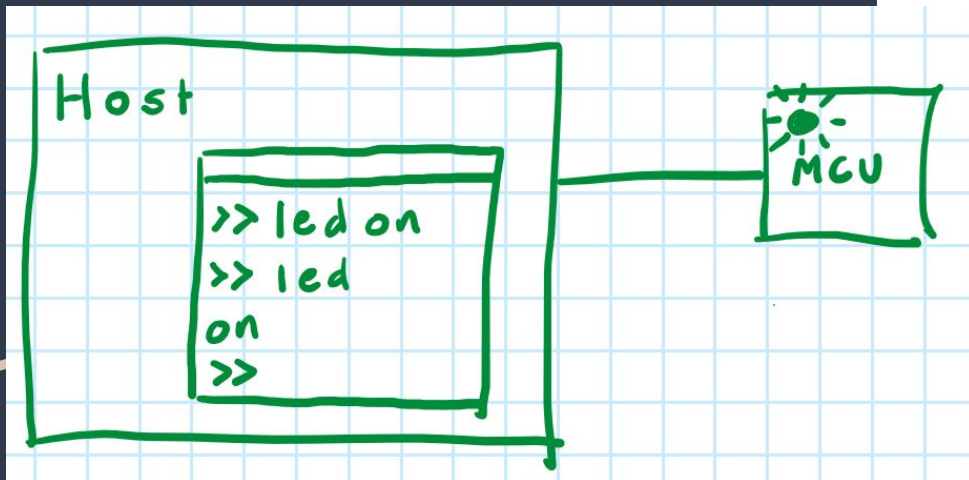


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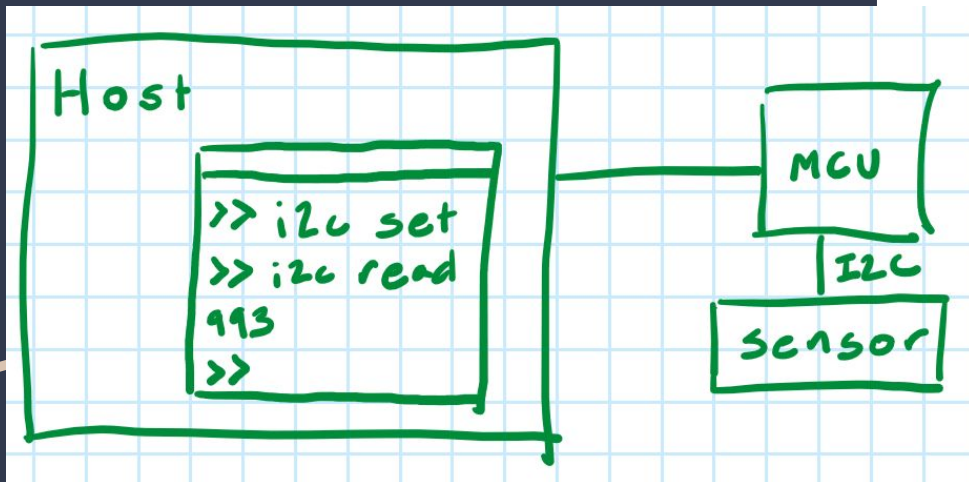


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- Control tasks
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- **REPL**
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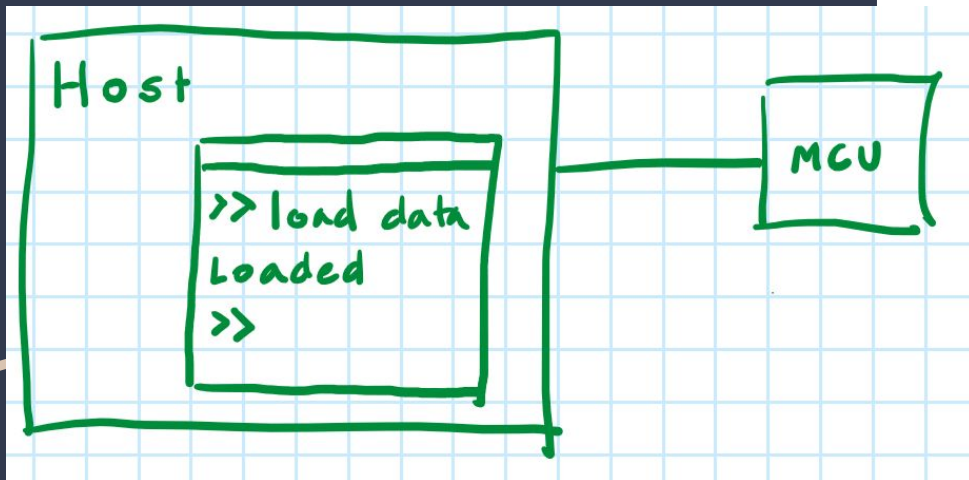


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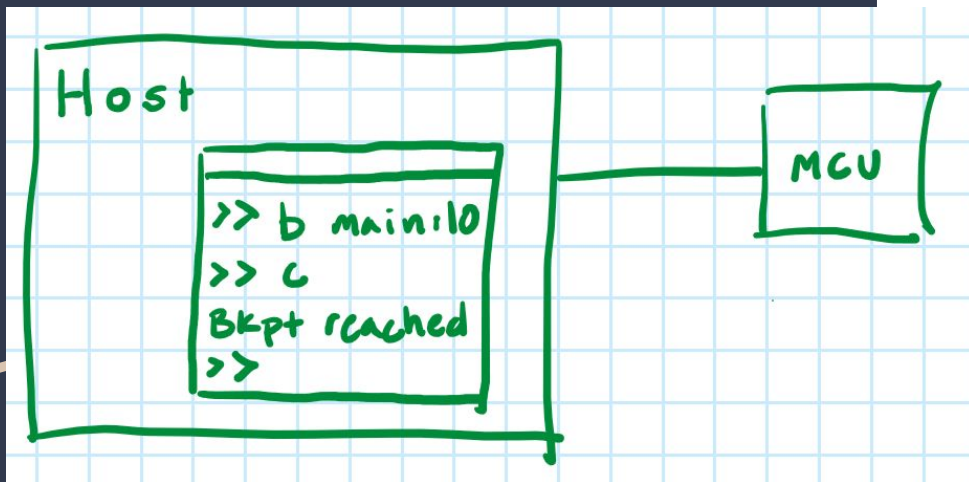


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- Control tasks
- Query state
- REPL
- Load data/firmware
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# Why and What is it?

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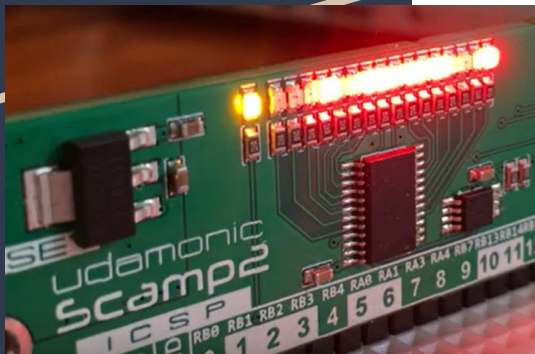


- Control tasks
- Query state
- REPL
- Load data/firmware
- On-chip debugging
- **Monitor/small OS**

```
: blinken
begin
    random leds
    blink
    key? until
    0 leds
;
ok

blinken|
```

## FlashForth



## microshell

```
uShell 0.1.0
[host /]$ ls
d---- .
d---- bin/
d---- dev/
d---- etc/
-r--- readme.txt
[host /]$ cat readme.txt
Welcome to MicroShell DEMO implementation!
You will see how most common features work.
Enjoy!
[host /]$
```



"The first thing I do in a new project is blink an LED. The next thing is to bring up a command-line shell. It's a great way to get stuff running quickly."

- andyturk (on the [EEVBlog forum](#))



# Command-Line Blinky

Message Dictionary	
on	Turns the LED on (at the last stored duty cycle & frequency)
off	Turns the LED off
dc <val>	Sets the duty cycle. Val is an integer percent value. Returns the current duty cycle if <val> is omitted.
freq <val>	Sets the blink frequency. Val is a float value in Hertz. Returns the current frequency if <val> is omitted.

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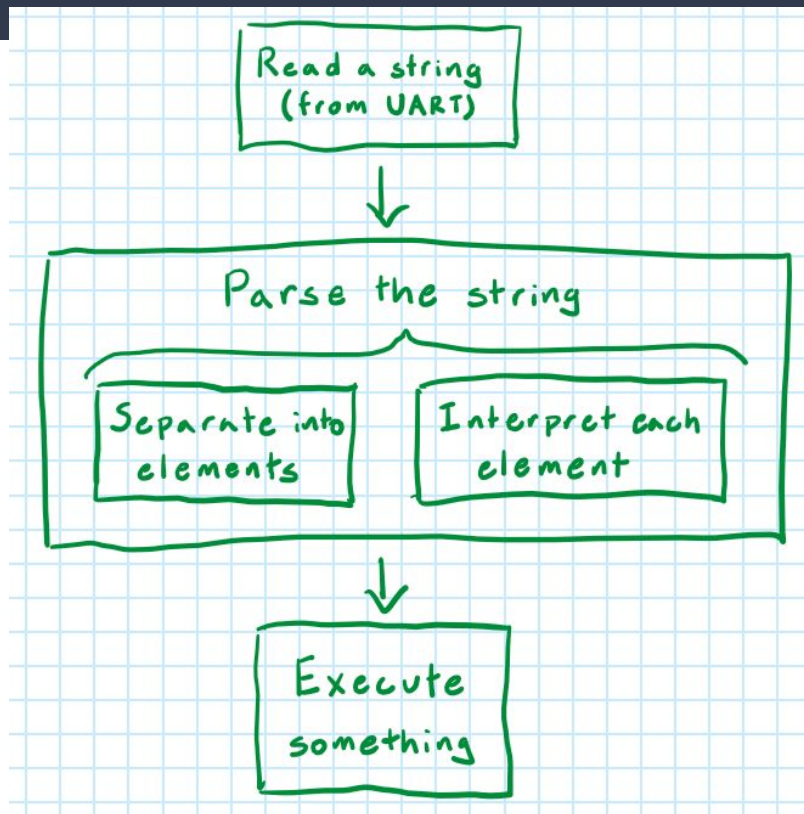


# Live Display of ADC Values with PyQt

Message Dictionary		
To	r	Requests an ADC value
From	<val>	4-digit ADC value in ASCII

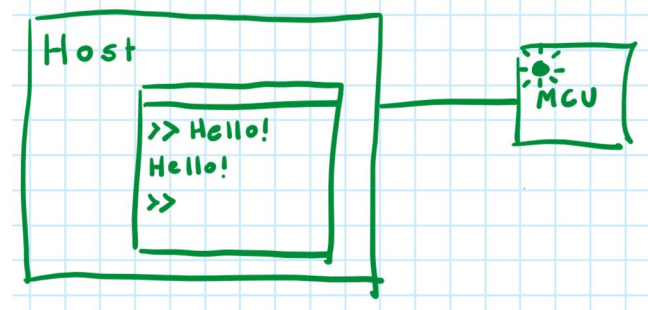
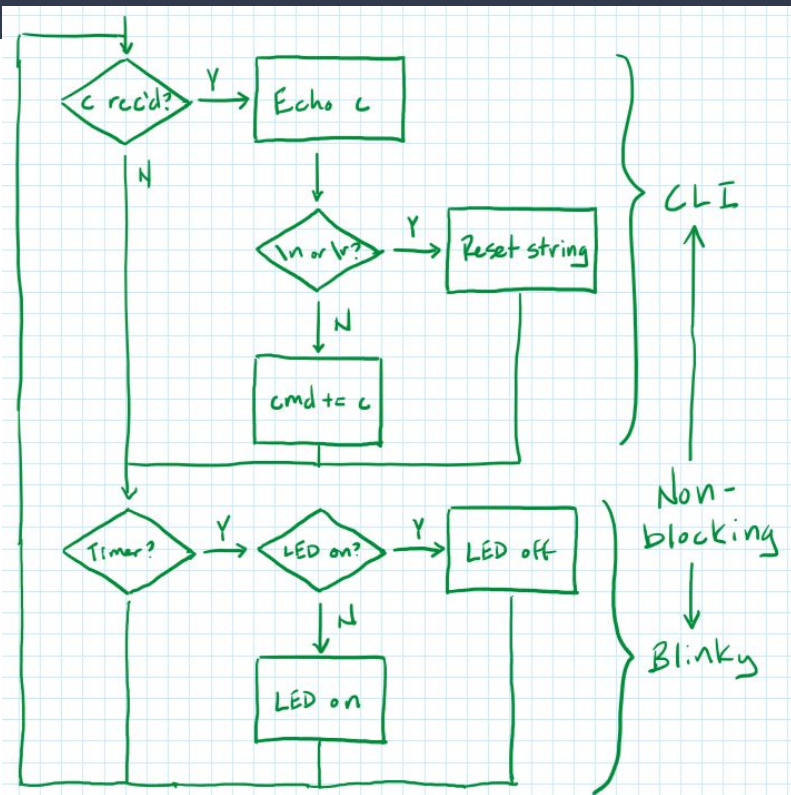
# Plan of Attack

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# Step 1: Read from UART

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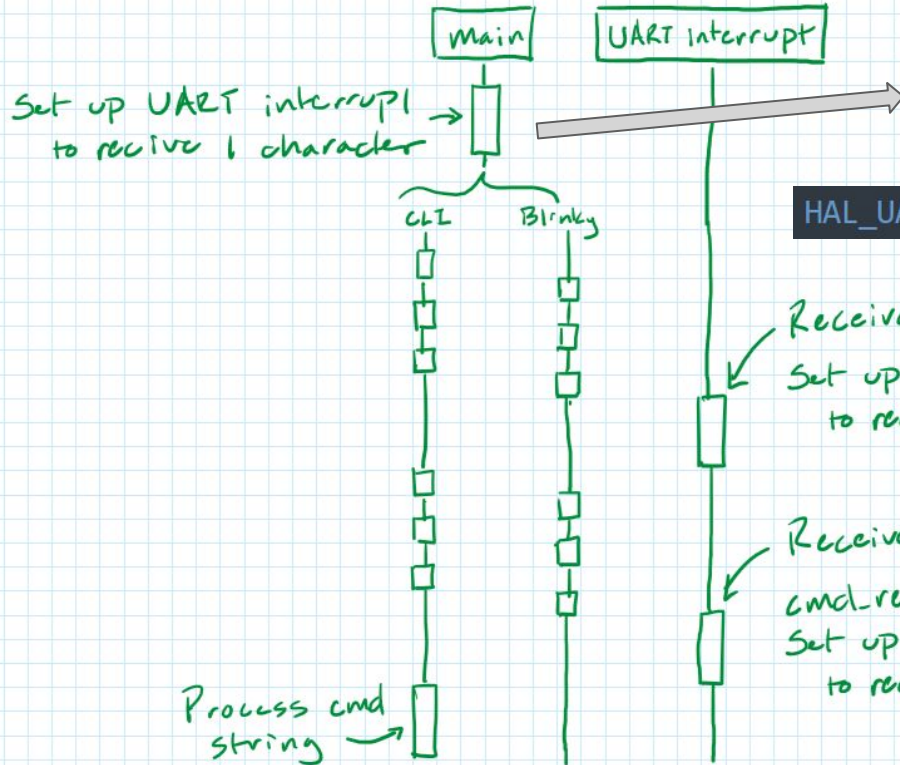


# Step 1: Read from UART

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~~Serial.available()~~



```
uint8_t cmd[MAX_CMD_LEN] = {0};
```

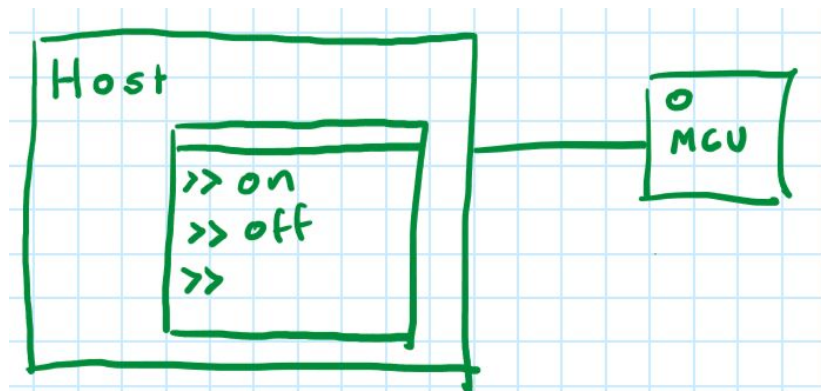
```
uint8_t * p_current_char = cmd;
```

```
HAL_UART_Receive_IT(&huart2, cmd, (size_t)1);
```

```
HAL_UART_Receive_IT(huart, ++p_current_char, (size_t)1);
```

# Step 2: Simple Commands

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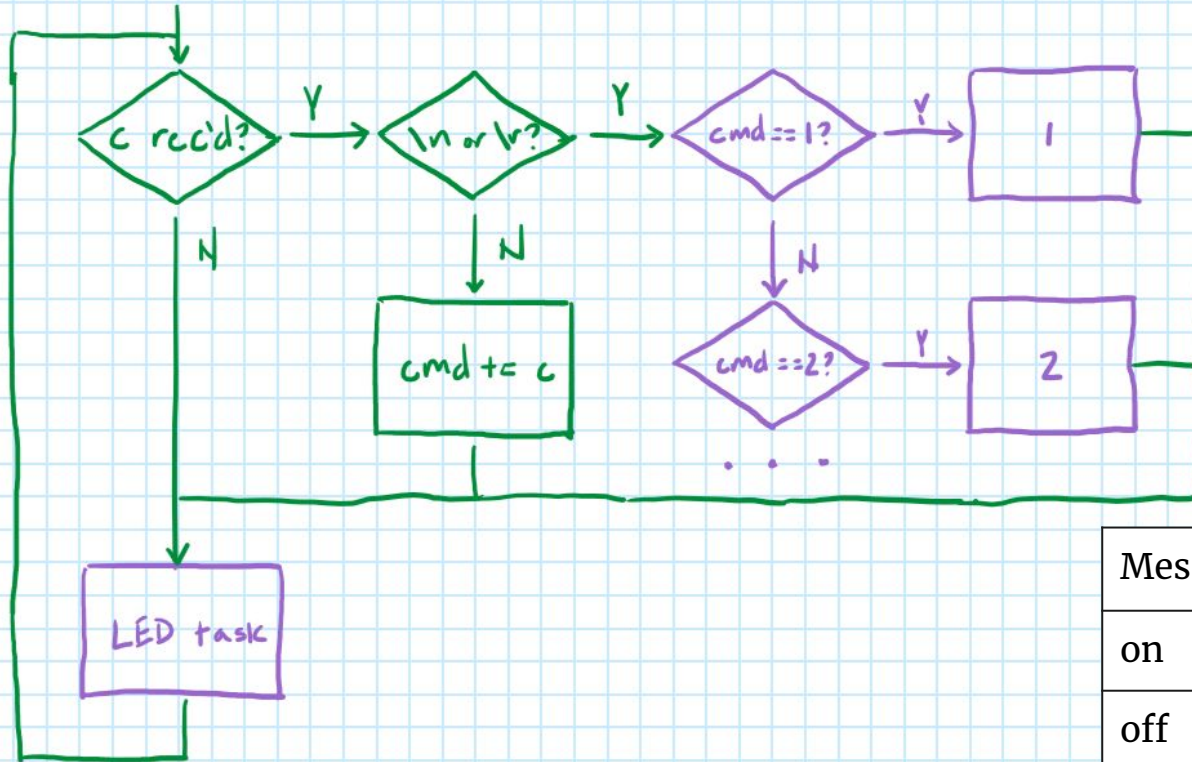
## Message Dictionary

on	Turns on the on-board LED
off	Turns off the on-board LED





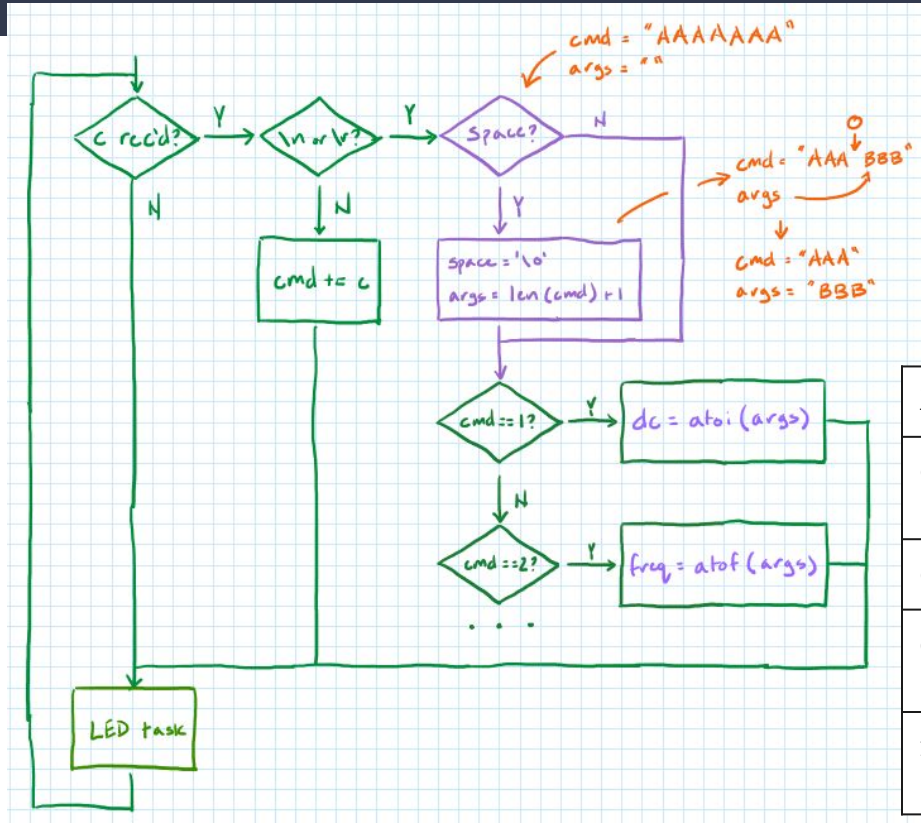
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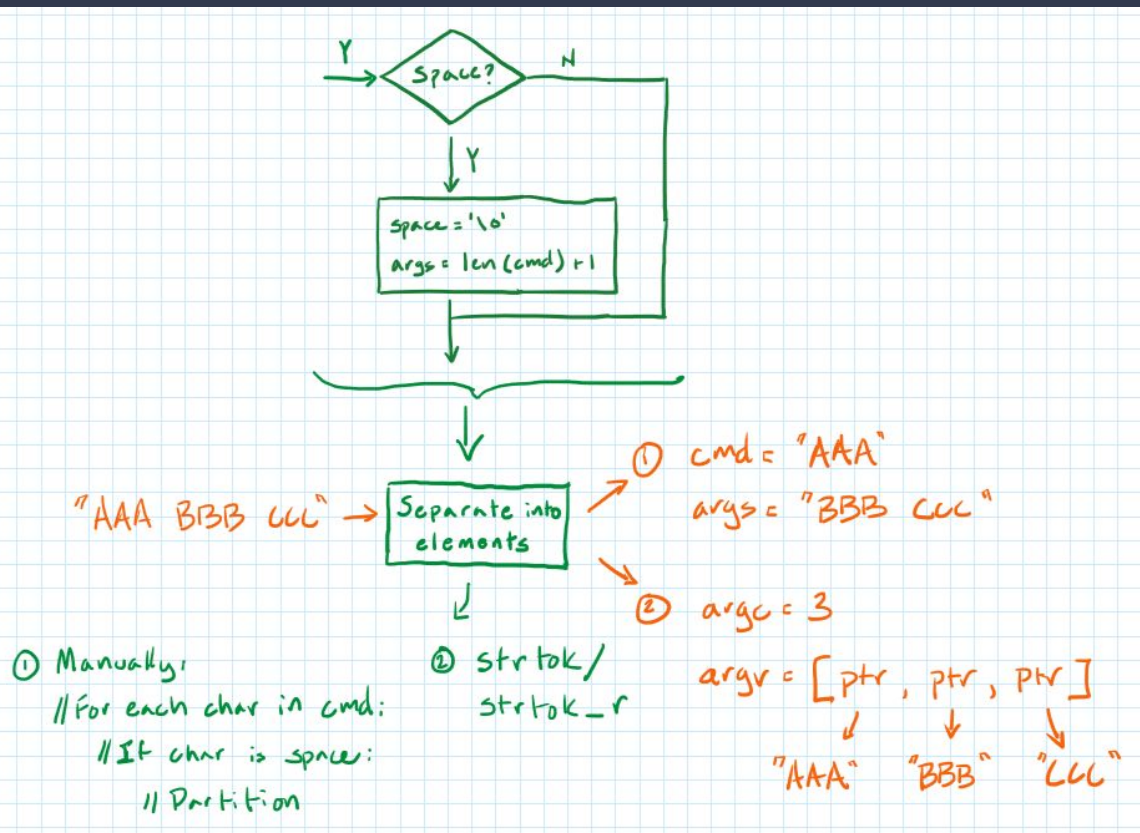


# Step 3: Commands + Values



Message Dictionary	
on	Turns the LED on (at the last stored duty cycle & frequency)
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# Step 3: Commands + Values



# Going Further

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## CLI Libraries

- [Anchor](#)
- [Memfault](#)
- [Args](#)
- [getopt](#) / [Gengetopt](#)
- [Docopt](#)
- [Tree-based CLI](#) from "[The Power of a LUT](#)"

## Architectural Improvements

- Wireless communication
- Modules/Message passing
- RTOS
- Double-buffering
- Security
- Framing
- Error checking



# Wireless CLI

Message Dictionary	
on	Turns the LED on (at the last stored duty cycle & frequency)
off	Turns the LED off
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freq <val>	Sets the blink frequency. Val is a float value in Hertz. Returns the current frequency if <val> is omitted.

# Going Further

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## Better line reading

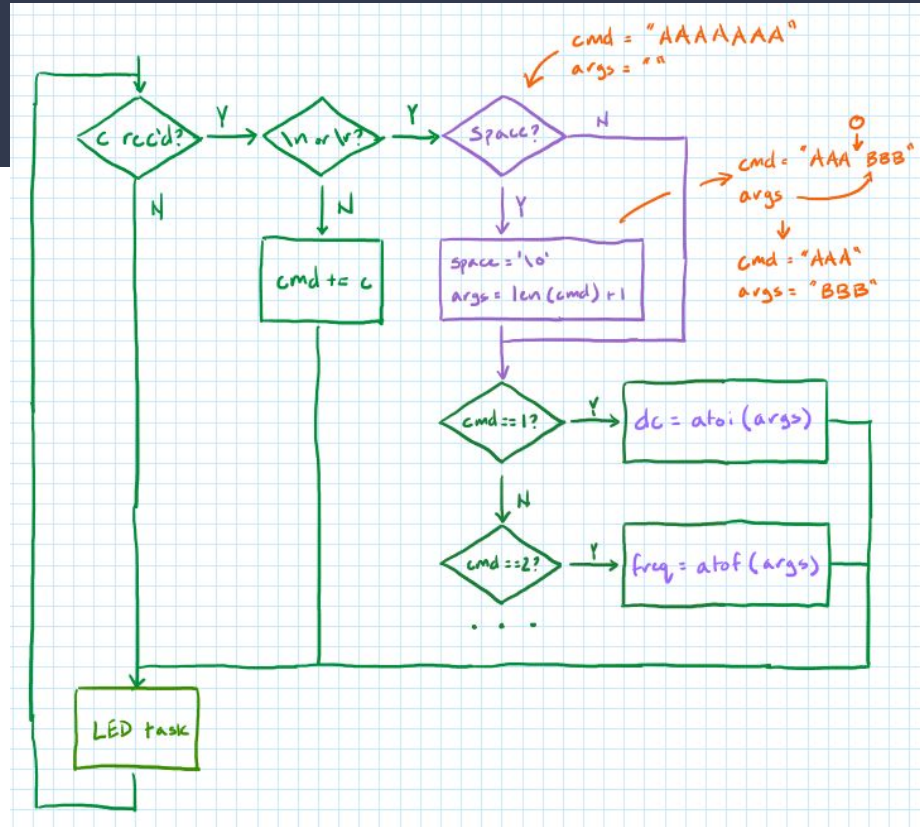
- [getline](#)
- [linenoise](#)

## Interpreters/Monitors/OSes

- [FlashForth](#)
- [uBASIC](#)
- [microshell](#)
- [RIDE Shell and C.impl interpreter](#) (ELLO computer)

## [On-chip Debugging](#) (Cortex-M)

# Summary



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Thank you for coming and  
I hope you enjoy the rest  
of the conference!